

Goethe-Center for Scientific Computing (G-CSC)
Goethe-Universität Frankfurt am Main

Modeling and Simulation I

(Practical SIM1, WS 2017/18)

Dr. A. Nägel, Dr. S. Reiter, Dr. M. Hoffer

Exercise sheet 5 (Due: Mo., 11.12.2017, 10h)

Exercise 1 (8P + 2P + 2P)

In Sheet02, Exercise 3 we solved the two-body system, consisting of the earth and an artificial satellite. Now, with far more capable numerical solvers, we can finally solve a much more realistic N-Body system, such as our own solar system. Analogous to Sheet02, Exercise 3, the force between two bodies $body_i$ and $body_j$ is defined as:

$$F_{ij} = Gm_i m_j \frac{\mathbf{r}_j - \mathbf{r}_i}{\|\mathbf{r}_j - \mathbf{r}_i\|^3} \quad (1)$$

where G is the gravitational constant, \mathbf{r}_i is defined as the location of $body_i$ and $\|\mathbf{r}_j - \mathbf{r}_i\|$ is the magnitude of the distance between \mathbf{r}_i and \mathbf{r}_j . The system of ODEs that describes the behavior of n bodies in space is defined as follows:

$$\begin{aligned} \frac{d^2 \mathbf{r}_1}{dt^2} &= \sum_{\substack{j=1 \\ j \neq 1}}^n Gm_j \frac{\mathbf{r}_j - \mathbf{r}_1}{\|\mathbf{r}_j - \mathbf{r}_1\|^3} \\ &\vdots \\ \frac{d^2 \mathbf{r}_i}{dt^2} &= \sum_{\substack{j=1 \\ j \neq i}}^n Gm_j \frac{\mathbf{r}_j - \mathbf{r}_i}{\|\mathbf{r}_j - \mathbf{r}_i\|^3} \\ &\vdots \\ \frac{d^2 \mathbf{r}_n}{dt^2} &= \sum_{\substack{j=1 \\ j \neq n}}^n Gm_j \frac{\mathbf{r}_j - \mathbf{r}_n}{\|\mathbf{r}_j - \mathbf{r}_n\|^3} \end{aligned}$$

Our simulation will start at 01.12.2017 and ends exactly 31558149 seconds later which is the duration of one earth orbit. The following bodies shall be simulated:

1. Sun
2. Mecerury
3. Venus
4. Earth
5. Moon (Luna)
6. Mars
7. Jupiter
8. Saturn
9. Uranus
10. Neptune
11. Comet Halley (1P)
12. Eros
13. Churiomov Gerasimenko (67P)

To acquire the initial values (mass, \mathbf{r} and \mathbf{v}), visit the NASA HORIZONS webpage (<http://ssd.jpl.nasa.gov/horizons.cgi>). To get data in the required format, the default settings have to be changed:

Current Settings

Ephemeris Type [\[change\]](#) : **VECTORS**
 Target Body [\[change\]](#) : **Mars [499]**
 Coordinate Origin [\[change\]](#) : **Solar System Barycenter (SSB) [500@0]**
 Time Span [\[change\]](#) : **Start=2017-12-01, Stop=2018-11-30, Step=1 d**
 Table Settings [\[change\]](#) : **quantities code=2; output units=KM-S; labels=NO**
 Display/Output [\[change\]](#) : *default* (formatted HTML)

Necessary changes in table settings:

Table Settings

Select vector table output

Type 2 (state vector {x,y,z,vx,vy,vz})

Optional vector-table settings:

output units :	km & km/s -- units to use for distance and velocity
reference plane :	ecliptic and mean equinox of reference epoch -- reference X-Y plane for vectors
reference system :	ICRF/J2000.0 -- reference frame for vector coordinates
aberrations :	Geometric states (no aberration; instantaneous ephemeris states) -- aberration correction
labels :	<input type="checkbox"/> -- enable labeling of each vector component
delta-T (TDB-UT) :	<input type="checkbox"/> -- output time-varying difference between TDB and UT time-scales
CSV format :	<input type="checkbox"/> -- output vector components in Comma-Separated-Variables (CSV) format
object page :	<input checked="" type="checkbox"/> -- include object information/data page on output

Use Settings Above Default Optional Settings Cancel

The settings are listed below:

Ephemeris:

- Ephemeris Type: Vector

Coordinate Origin:

- Coordinate Origin: Solar System Barycenter (SSB) [500@0]

Time Span:

- Time Span: 2017-12-01 to 2018-11-30, 00:00
Format: (yyyy-mm-dd, HH-MM)

Table Settings:

- Output Units: km & km/s
- Quantities Code: 2 (state vector {x,y,z,vx,vy,vz})

After adjusting the settings, click “Generate Ephemeris”. The result is shown as html output, which will look like this:

```
Results
*****
Ephemeris / WWW USER Fri Dec 1 05:50:20 2017 Pasadena, USA / Horizons
*****
Target body name: Sun (10) {source: DE431mx}
Center body name: Solar System Barycenter (0) {source: DE431mx}
Center-site name: BODY CENTER
*****
Start time : A.D. 2017-Dec-01 00:00:00.0000 TDB
Stop time : A.D. 2018-Nov-30 00:00:00.0000 TDB
Step-size : 1440 minutes
*****
Center geodetic : 0.00000000,0.00000000,0.00000000 {E-lon(deg),Lat(deg),Alt(km)}
Center cylindric: 0.00000000,0.00000000,0.00000000 {E-lon(deg),Dxy(km),Dz(km)}
Center radii : (undefined)
Output units : KM-S
Output type : GEOMETRIC cartesian states
Output format : 2 (position and velocity)
Reference frame : ICRF/J2000.0
Coordinate systm: Ecliptic and Mean Equinox of Reference Epoch
*****
JDTDB
 X Y Z
VX VY VZ
*****
$$SOE
2458088.500000000 = A.D. 2017-Dec-01 00:00:00.0000 TDB
X = 2.962290237798805E+05 Y = 8.933135568594927E+05 Z = -1.862353462813556E+04
VX = -9.697674894574029E-03 VY = 9.055119172640794E-03 VZ = 2.323585079015175E-04
2458089.500000000 = A.D. 2017-Dec-02 00:00:00.0000 TDB
X = 2.953905510063761E+05 Y = 8.940954331161901E+05 Z = -1.860344227345183E+04
VX = -9.711409762306828E-03 VY = 9.043870924106768E-03 VZ = 2.327424977207775E-04
2458090.500000000 = A.D. 2017-Dec-03 00:00:00.0000 TDB
```

The object properties, such as mass, can be found in the “Object Data Page”:

- (c) Simulate the time intervals $[t_0 = 0, t_n = 10 \text{ years}]$ and $[t_0 = 0, t_n = 100 \text{ years}]$. Please note that on older machines the computation can take a while. It is advised to filter the solution trajectory, e.g., only add every n -th value to the solution. For the last interval, it is allowed to increase the *TOL* value to $1e-2$ if your computer is too slow. If you do so, specify the *TOL* value that has been used for the computation.

Exercise 2 (3 Points)

Design and simulate your own solar system with at least 3 bodies.

Exercise 3 (5 Bonus Points)

Write a VRL component that reads the Ephemeris data from the HORIZONS web interface. Plot the difference between the computed trajectory by your ODE solver for planet earth and the trajectories published by NASA. The result is a sufficient estimate for the global error.

Remark: Send your implemented source code as VRL-Studio project (.vrlp file) and the answers to the questions as plain text in an email. Append the pdfs produced with the TrajectoryPlotter to the email.

Send your solution to `practical.sim1@gcsc.uni-frankfurt.de` until Monday, 11.12.2017, 10h.